BALLIN et al
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AMENDMENTS TO THE ABSTRACT:

Please amend the Abstract as shown on a separate page attached hereto.



A hierarchical behavioural behavioral framework is used to generate and control autonomous and semi-autonomous behaviour behavior in an articulate object. A behavioural behavioral controller is arranged to receive input associated with a behavioural behavioral action, to infer a plurality of behavioural behavioral parameter values using the framework, and to generate equivalent behaviour behavior in the articulate object using the parameter values when loaded in the behavioural behavioral controller to generate output corresponding to the equivalent behaviour behavior may reproduce the inputted behavioural behavioral action, and /or comprise include one or more other behavioural behavioural actions, which may be performed simultaneously or as part of a sequence of actions.